

Parallel Computing Applied to Satellite Images Processing for Solar Resource Estimates

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1 Introduction

- General introduction
- Solar irradiation model and satellite data bank

2 problem description

- problem overview and description

3 parallel implementation

- parallel model
- algorithm description

4 performance evaluation

- Test set, methodology and environment
- Evaluation results

5 Conclusions

- Conclusions and future work

INTRODUCTION: SOLAR RESOURCE OVERVIEW

Objective:

- Estimate the amount of solar energy that reaches ground level.
- Solar energy applications, meteorology, agronomical planning.
- This work: parallel computing for satellite-based estimation.
- This work: first step for migrating to a C platform using parallel computing strategies.

Uruguay's solar resource knowledge context:

- First Uruguayan Solar Map (2009).
- First satellite-based solar resource model (2011).
- Next: improvement (2012), **optimization** and operation.

Why a satellite-based irradiation model?

- Spatial resolution ≈ 2 km. Hourly or intra-hourly estimates.
- **Satellite-based estimates provides better accuracy than interpolation of ground measurements for sites located more than 30 km away from the measuring stations.**

INTRODUCTION: SOLAR RESOURCE MODEL

- Justus, Paris and Tarpley hourly irradiation model (1986).
- Statistical model which relies on a multiple regression.
- Adjusted for the target region using ground measurements.
- A spatial neighborhood of sites is used (**cells**).

Multiple regression model:

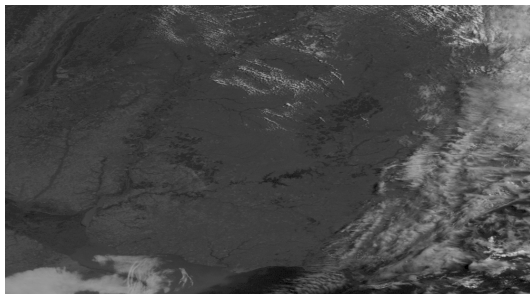
$$I = I_{sc} \left(\frac{r_0}{r} \right)^2 \cos \theta_z (a + b \cos \theta_z + c \cos^2 \theta_z) + d (B_m^2 - B_0^2)$$

- I_{sc} - Hourly value of the solar constant.
- $(r_0/r)^2$ - Eccentricity factor (due to Sun-Earth distance).
- $\cos \theta_z$ - Cosine of the solar zenith angle.
- B_m - Mean brightness at the observed cell.
- B_0 - Clear-sky brightness for the observed cell.

INTRODUCTION: SATELLITE IMAGES DATABASE

- Cloud information is taken from the visible channel.
- More than 10 years of GOES-East images are available.

satellite	start date	end date	images
GOES 8	01/01/2000	31/03/2003	24750
GOES 12	01/04/2003	14/04/2010	51900
GOES 13	14/04/2010	30/04/2012	15300
total	01/01/2000	30/04/2012	91950



Mean Brightness B_m

- Is **calculated** for every site.

Clear-sky Brightness B_0

- A model is **trained** for every site.

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PROBLEM OVERVIEW

- Compute B_m mean brightness for every cell as an average.
- NetCDF format: standard machine-independent data format.
- Every image contains data and navigation information.

How many cells and images?

- Regular grid with a 5×5 latitude-longitude spacing.
- Target region varies between: 30 and 35 degrees South.
53 and 59 degrees West.
- A total of $(5 \times 30) \times (6 \times 30) = 27000$ sites for every image.

A total of 27000 sites shall be processed for more than 90000 images. Thus, approximately **2430 million averages** are to be computed in order to process the whole satellite database.

- Without using parallel computing: **15 hours** are needed to process the data bank in a single PC/server machine.

PROBLEM DESCRIPTION

Performance oriented point of view:

- Processing a single image takes a reduced execution time.
- Each image can be efficiently processed by a single processor.
- Complexity relies on the large number of images to process.

Context: first step towards a operational parallel platform

- Not only the main parallel algorithm was developed.
- A set of common libraries were built (for similar or future algorithms): implemented libraries are independent from any parallelization scheme.
- User parameters are introduced via plain text:
 - latitude-longitude spacing, target window.
 - folders, years of images to process, etc.
- Platform selection: C language and MPI standard.

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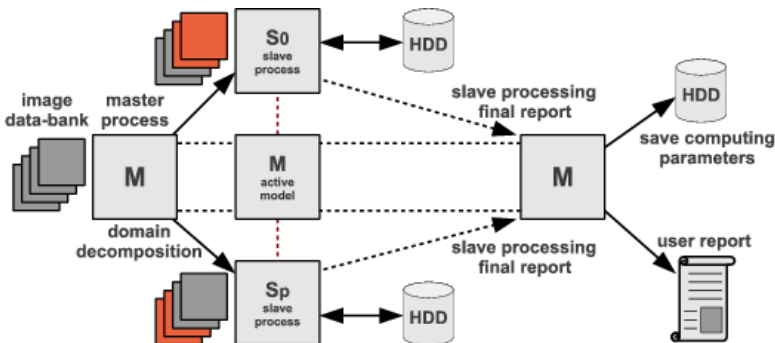
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PARALLEL MODEL

- A data-parallel scheme was adopted.
- Master process performs the **domain-decomposition**.
- An **active master-slave** model is used.
- Several processes are used which execute in different nodes.
- Every process receives a reference of the first and last image.



IMPLEMENTED LIBRARIES

Modularity: three main libraries were developed.

- (a) a *processing* library.
- (b) an *assignment* library.
- (c) a *calibration* library.

Processing library

- Implements all functionalities required for image processing.
- Features: interact with NetCDF files and disk writing.
- Start and finish image is received as a parameter (assignment).

Assignment library

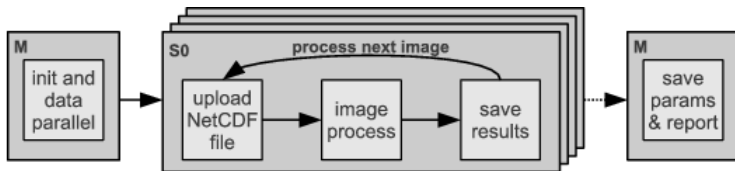
- Able to count how many images were requested to process.
- Logic to assess the domain-decomposition.

Calibration library

- Satellite calibration and count-to-radiance conversion.

ALGORITHM DESCRIPTION

- The well-known MPICH implementation was used (1.2.7p1).
- Algorithm flow:
 - (a) initialization and data parallel distribution.
 - (b) image upload from hard-disk.
 - (c) computation of the B_m values for each assigned image.
 - (d) save processed data to hard-disk.
- Master process is in charge of the initialization.
- Every slave process knows all the data to work independently.
- When a process finishes it sends a notification to the master.



LOAD BALANCING AND OUTPUT

Load balancing

- All the images in the data-bank:
 - have the same size and data.
 - image processing is exactly the same.
- The parallel algorithm was conceived to execute in a dedicated parallel computing infrastructure.
- **A static load balancing was adopted.**
- In practice, when processing ~ 7700 images (one year)
 - 20 images maximum deviation from the ideal situation.
 - correspond to a negligible value of ~ 10 seconds.

Algorithm's output

- Six plain text files with the grid values.
- Brightness counts and subproducts from the image calibration.
- Mask for corrupted values. The amount of pixels for average.

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TEST SET, METHODOLOGY AND ENVIRONMENT

Execution platform: Cluster FING

- Server with two Intel quad-core Xeon processors at 2.6 GHz, with 8 GB RAM, CentOS Linux, and Gigabit Ethernet.

Image test set:

- Satellite images of the year 2011 were used (7670 images).
- Disk capacity of 60GB. Local to the node used for evaluation.

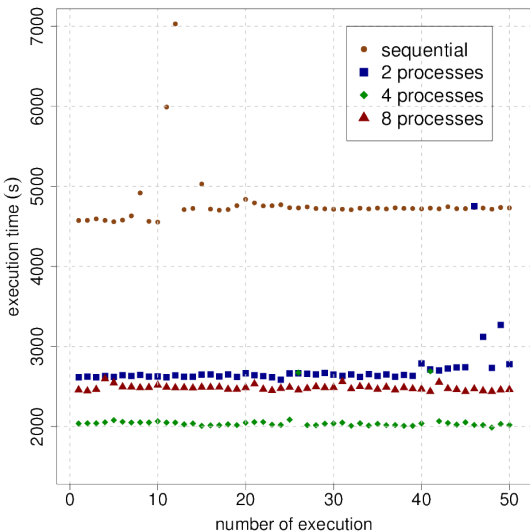
Performance metrics:

- 50 independent executions varying processes' amount.
- Speed up: compare the mean values of the sequential and parallel execution times (non-deterministic algorithms).
- Efficiency: is the normalized value of the speedup with the number of computing elements.

$$S_m = \frac{E[T_1]}{E[T_m]}$$

$$e_m = \frac{S_m}{m}$$

EXECUTIONS TIMES (1)



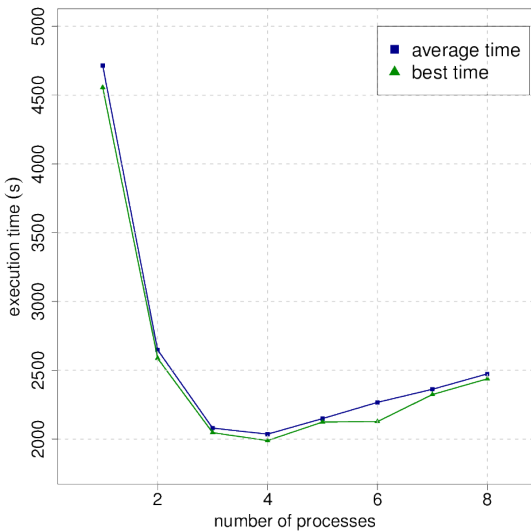
EXECUTIONS TIMES (2)

Experimental results

processes	execution time (s)			metric	
	best	avg	σ	speedup	efficiency
1 (sequential)	4555	4786	380	–	–
2	2587	2720	316	1.76	0.88
3	2047	2123	214	2.25	0.75
4	1989	2062	130	2.32	0.58
5	2124	2200	136	2.18	0.44
6	2127	2360	293	2.03	0.34
7	2324	2370	36	2.02	0.29
8	2438	2484	32	1.93	0.24

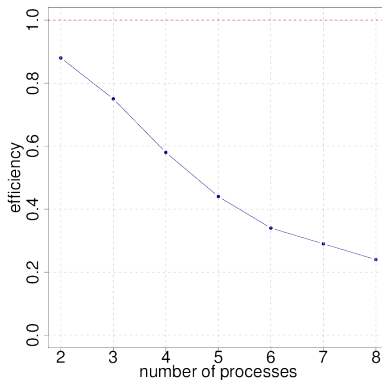
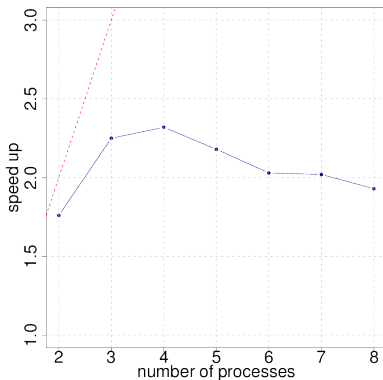
- Performance increase with processes' number for $p \leq 4$.
- A speedup of 1.76 is achieved when using $p = 2$.
- A maximum speedup of 2.32 is obtained at $p = 4$.
- When using more than 4 processes execution times increase.
- Standard deviation reduce when more processes are used.

EXECUTIONS TIMES (3)



SPEED UP AND EFFICIENCY

- Speed up presents a maximum at $p = 4$.
- Efficiency presents a maximum at $p = 2$.
- **Problem: limited input/output disk access bandwidth.**



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CONCLUSIONS AND FUTURE WORK

Conclusions:

- We present a parallel algorithm application to process satellite image information for solar resource estimates.
- The problem's complexity lies in the big amount of images.
- A parallel master-slave algorithm was developed based on image domain-decomposition.
- A maximum speedup of 2.32 was reached using 4 processes.
- Current version: it can't escalate beyond 4 processes because of the limited hard-disk drive input/output capacity.

Possible ways to improve algorithm's performance:

- Dynamic load balancing to execute in non dedicated infrastructures.
- Parallelization of hard-disk drive access.



¡Muchas Gracias!

Thank you!

Questions?